

Cross-well EM: Technology for reservoir monitoring, image and characterization

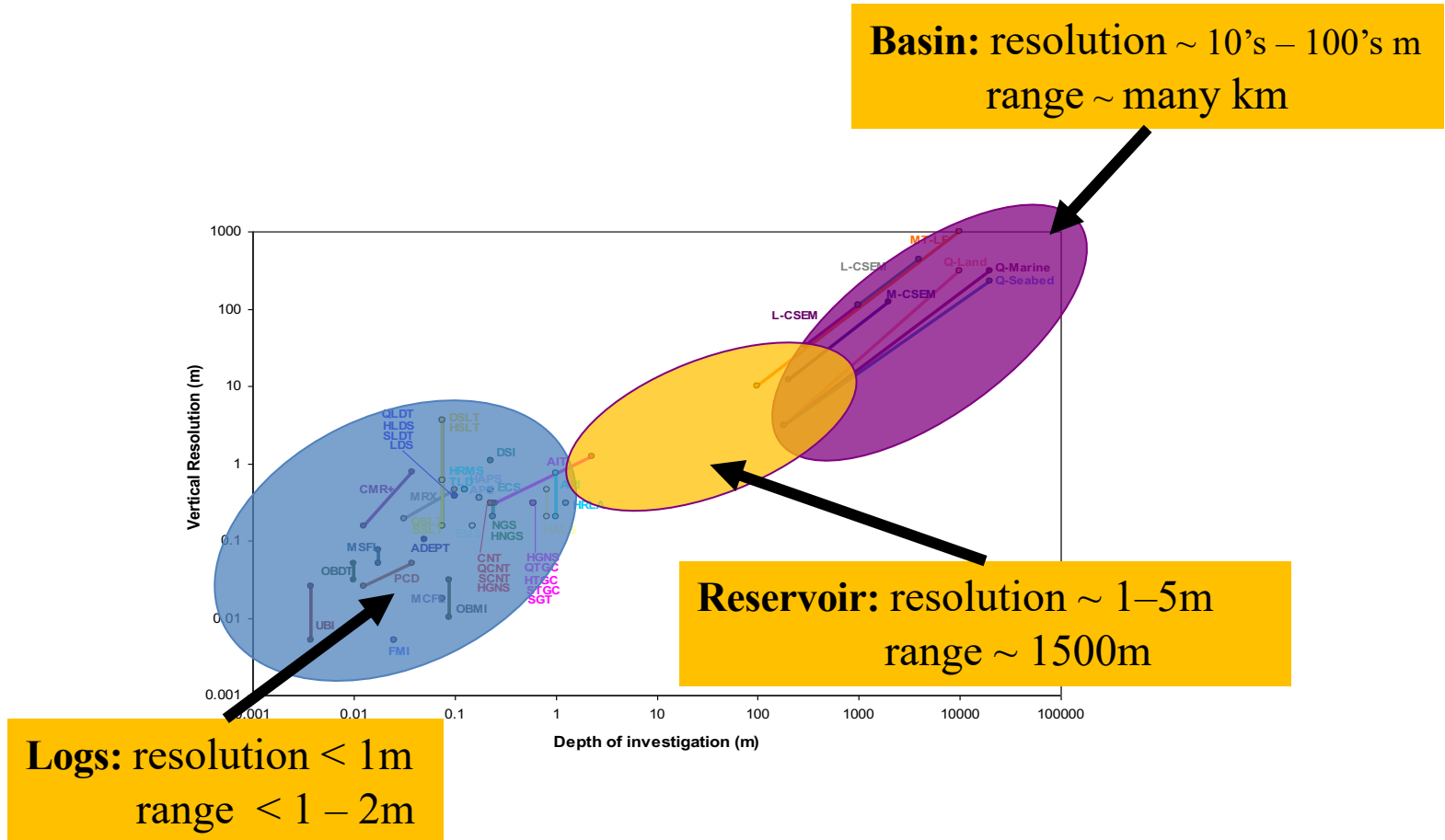
Ping Zhang



Agenda

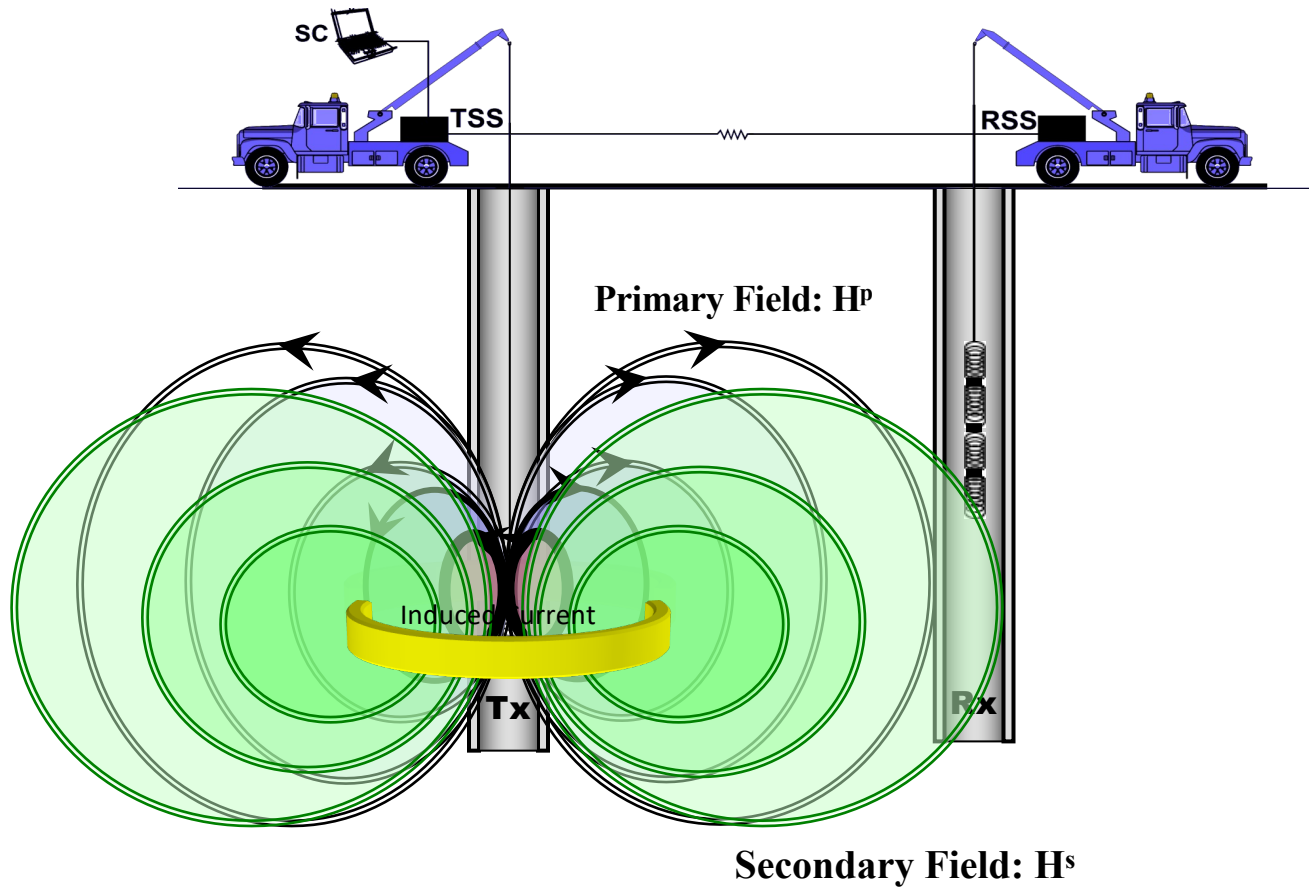
- Introduction
- Cross-Well EM Technology
- Case Histories
- Conclusion

EM Survey Methods

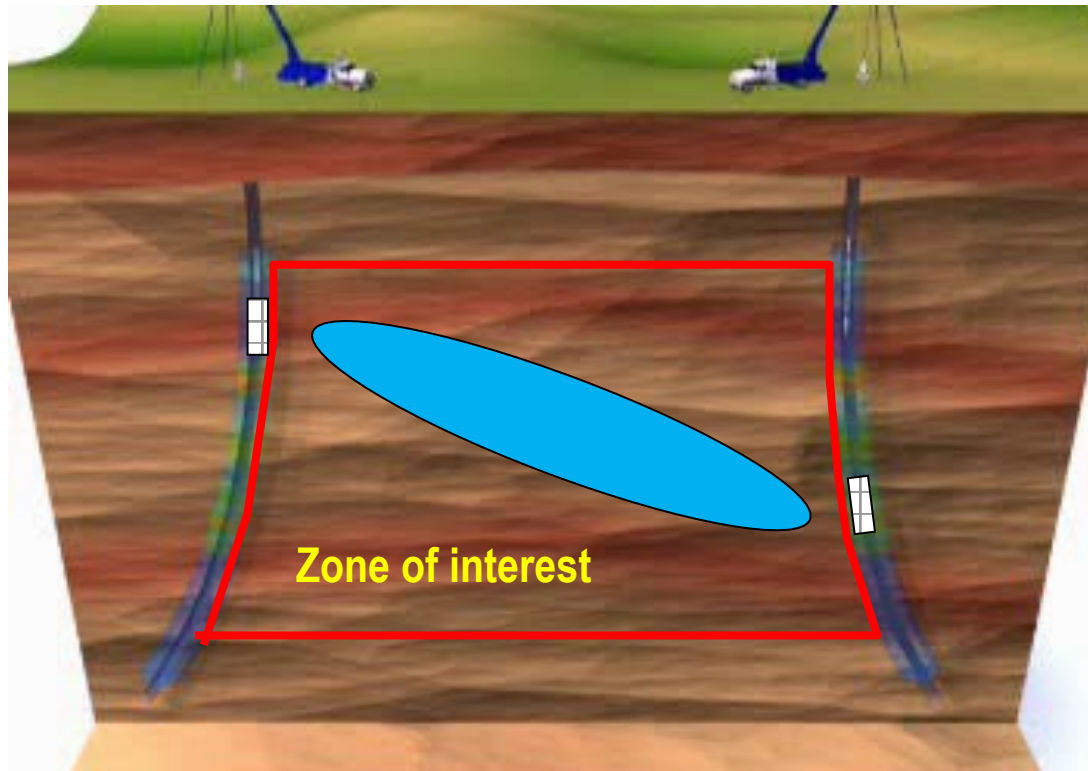


Cross-well EM technology

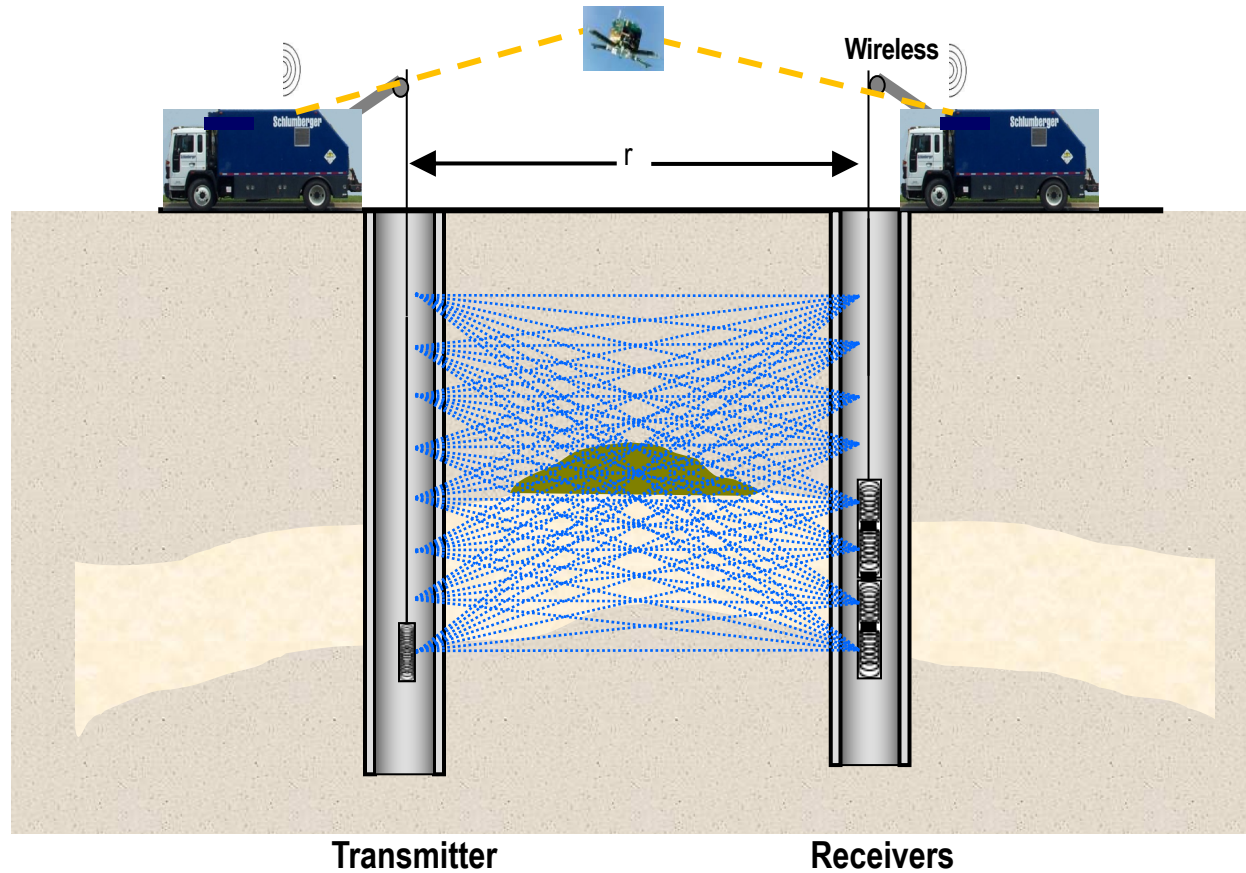
The Measurement Principle of Cross-Well EM



Inter-Well Region Interrogated by Tomography



Cross-Well EM Tomography



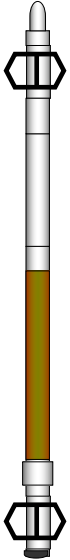
Tool Specifications

Well type and separation

Transmitter

OD: 3 3/8" (86mm)

Length: 9.88m



Receivers

OD: 2"1/8 (54mm)

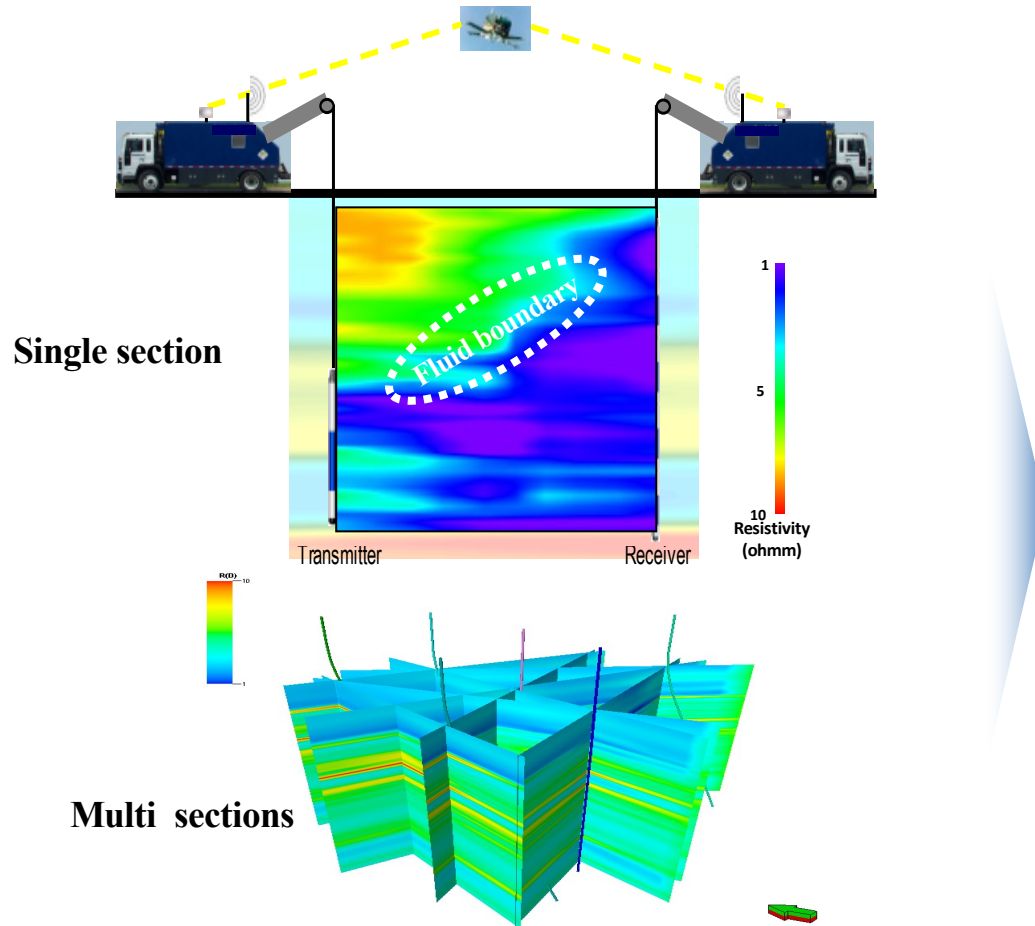
Length: 22.5m for 4 receivers



Optimized at frequencies
from 10-1000 Hz

Transmitter Well	Receiver Well	Max Spacing
Open	Open	1500m
Fiberglass	Fiberglass	1500m
Open	Steel casing	700m
Steel casing	Steel casing	n/a

Cross-well EM Applications



Applications

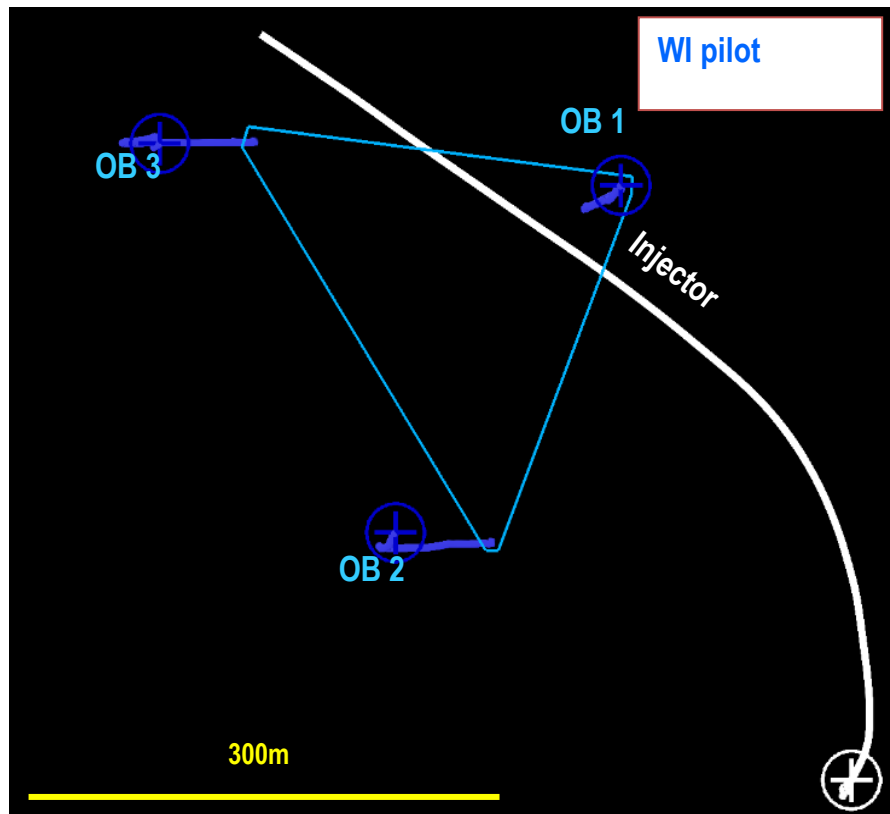
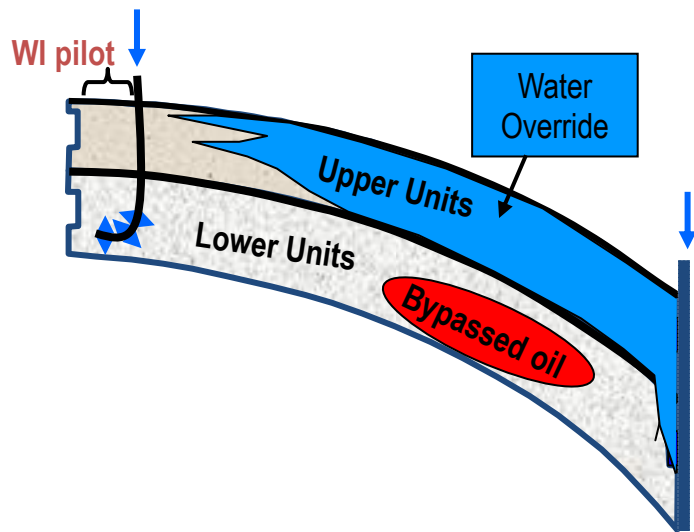
- Fluid front monitoring
- Identification of bypassed pay
- Enhanced reservoir characterisation & modelling
- Drilling optimisation

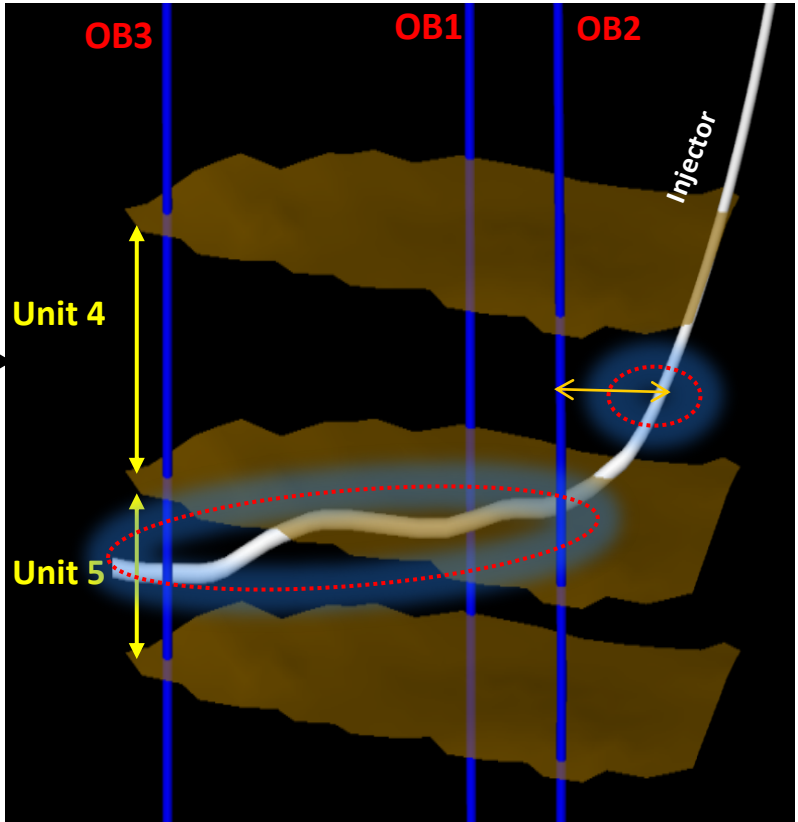
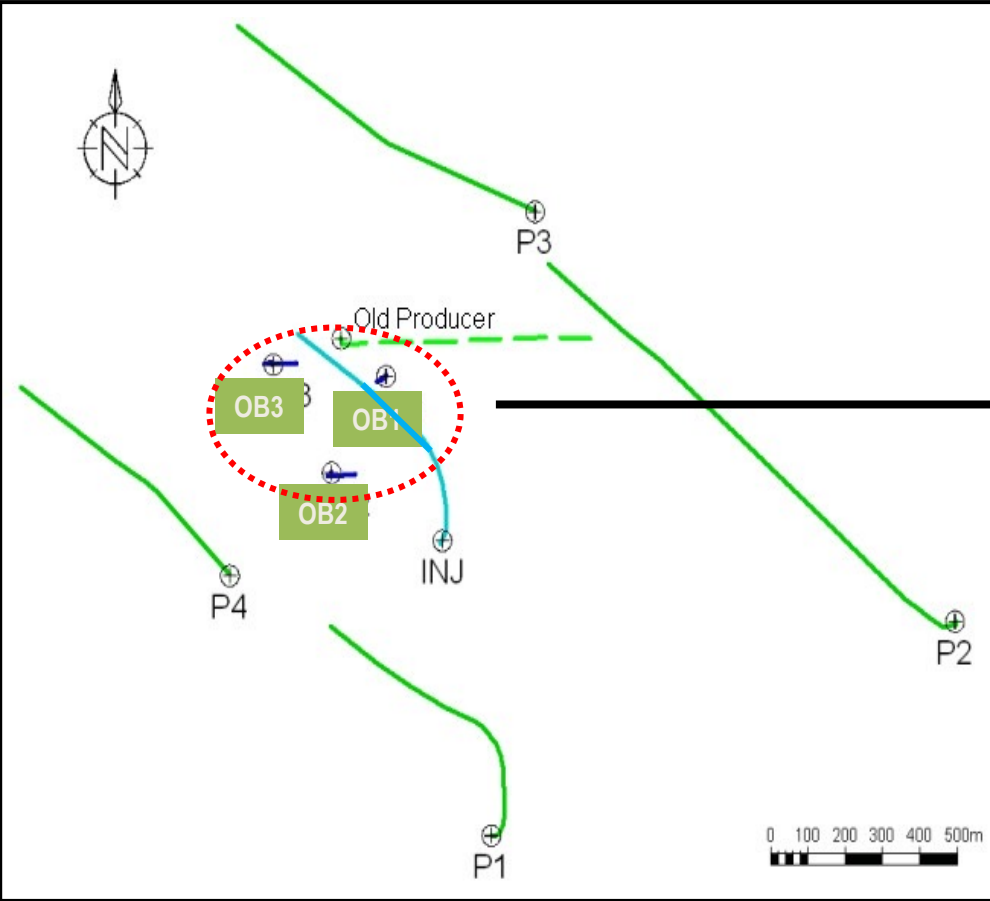
Monitoring Water Flood



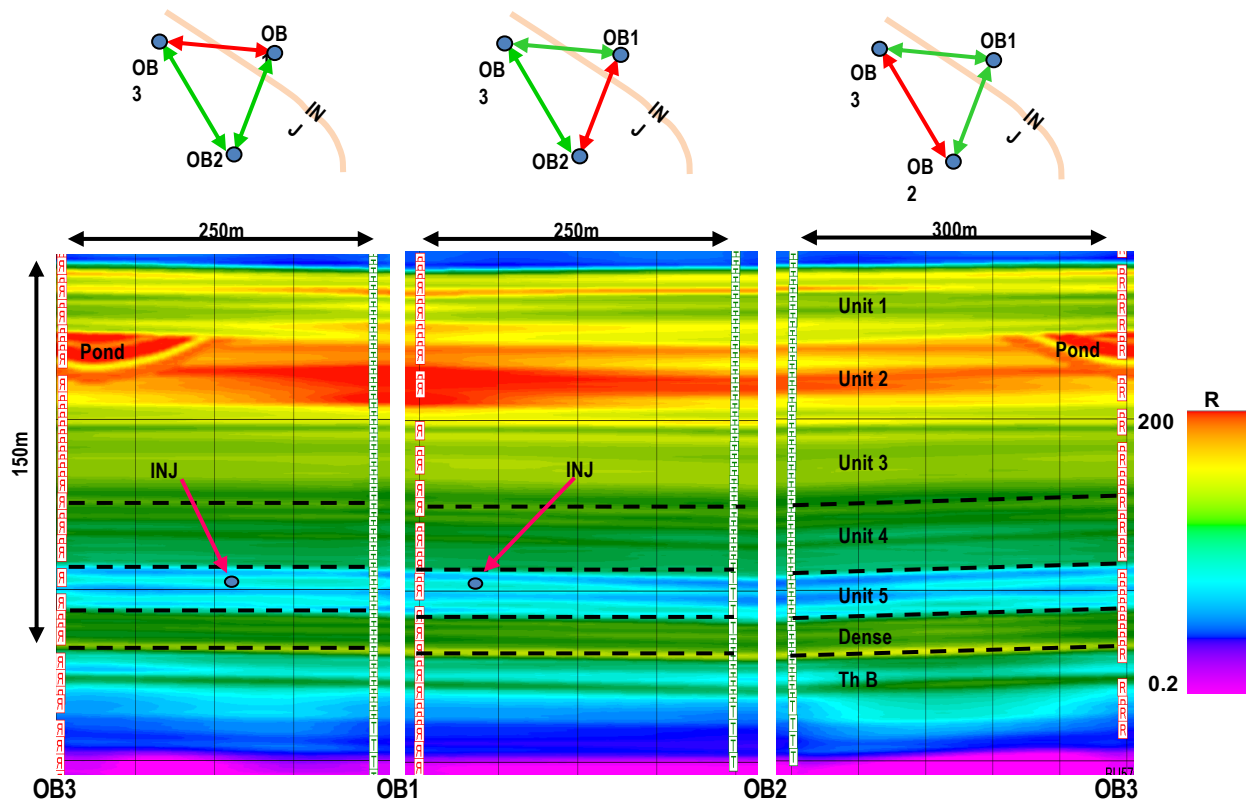
Permeability ranges from 1 md to 500 md

Peripheral water in uppermost reservoir units (high permeability)

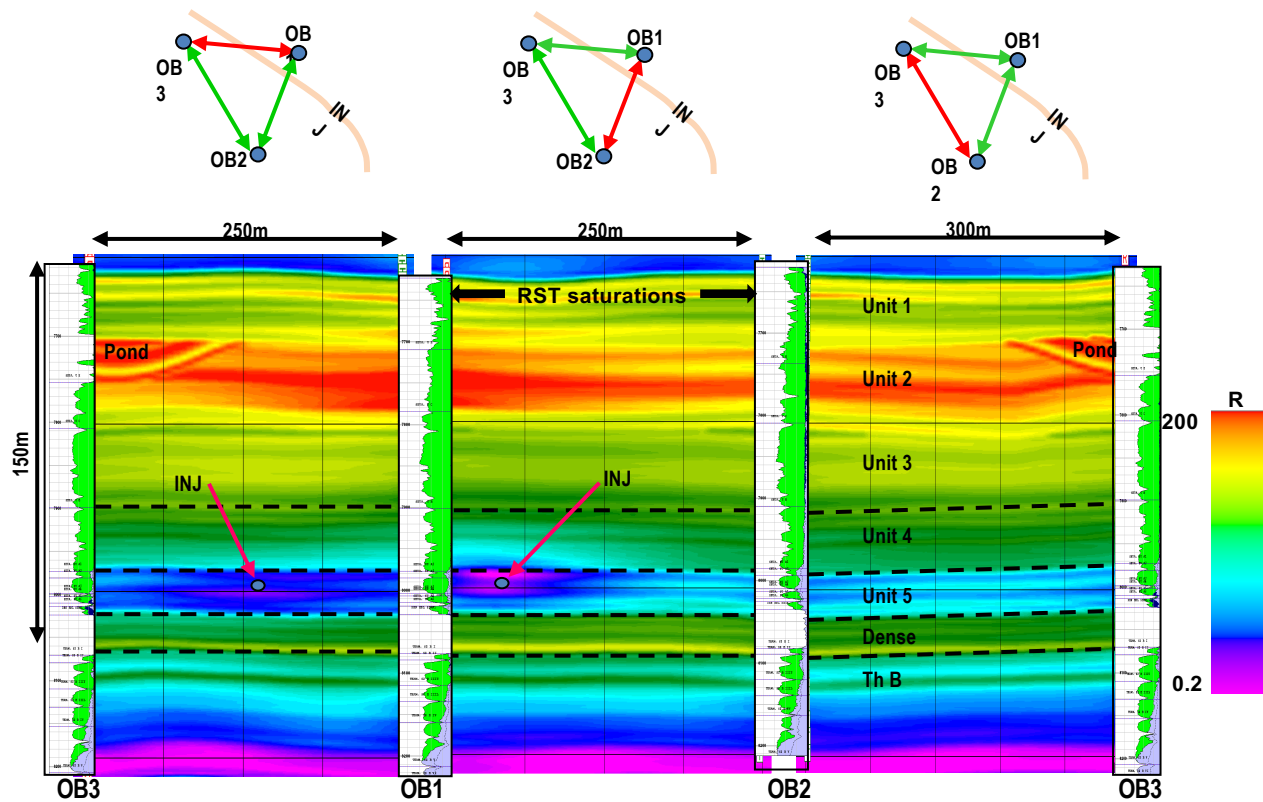




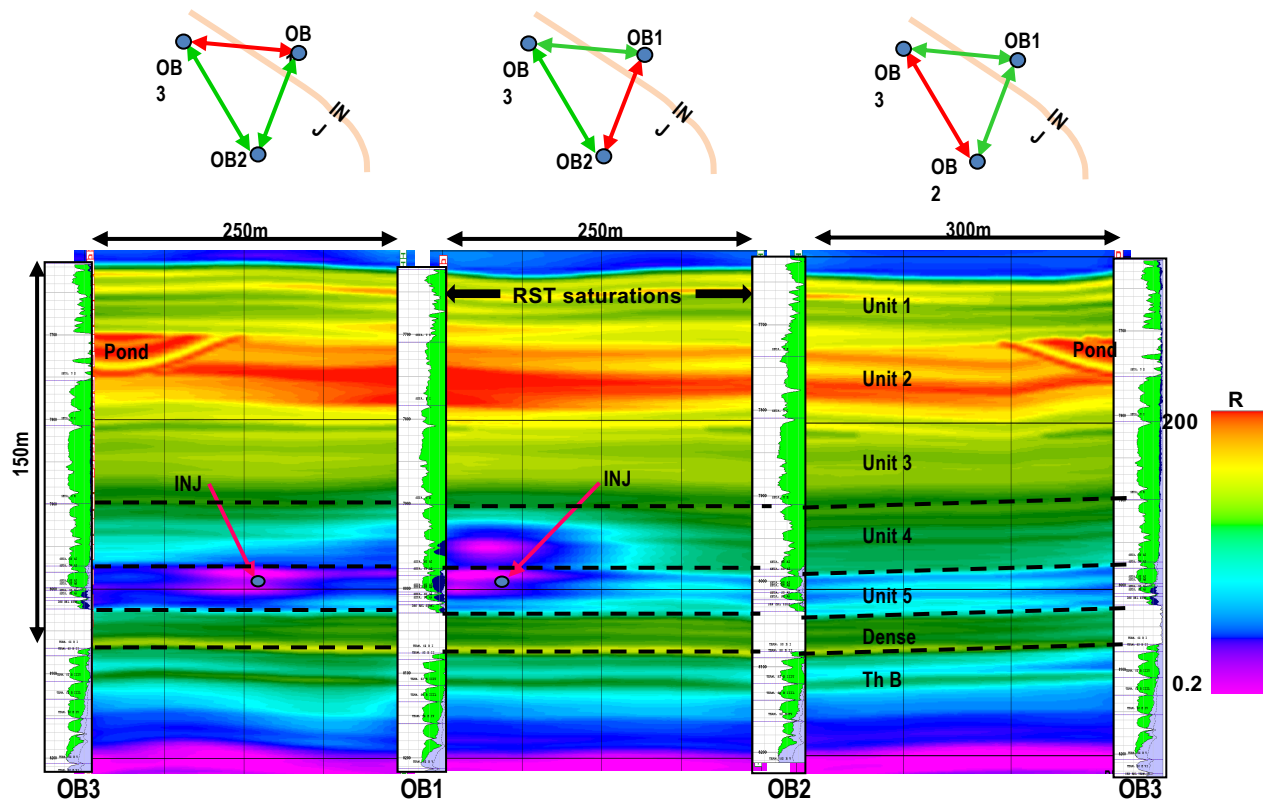
Permeability: unit 4 ~max 50md
unit 5 ~max 15md



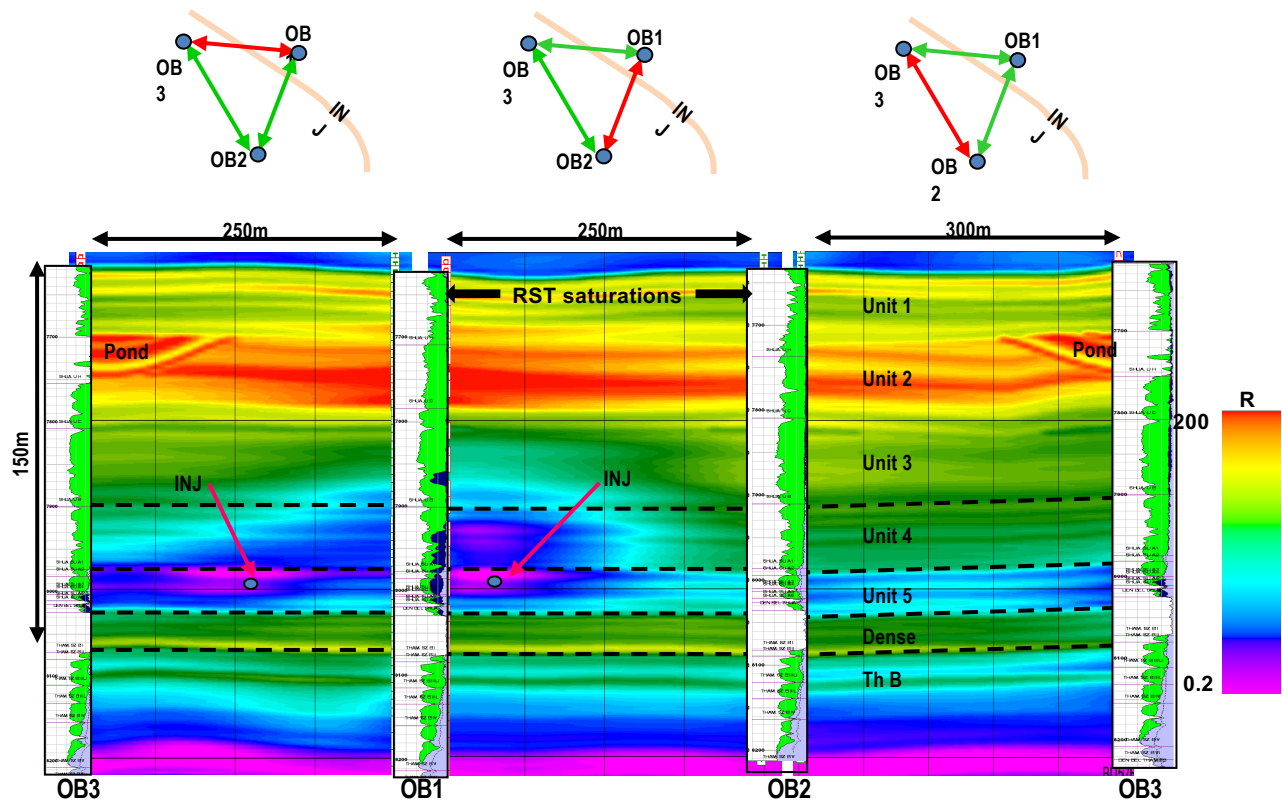
Baseline survey (September 2007, before the injection)



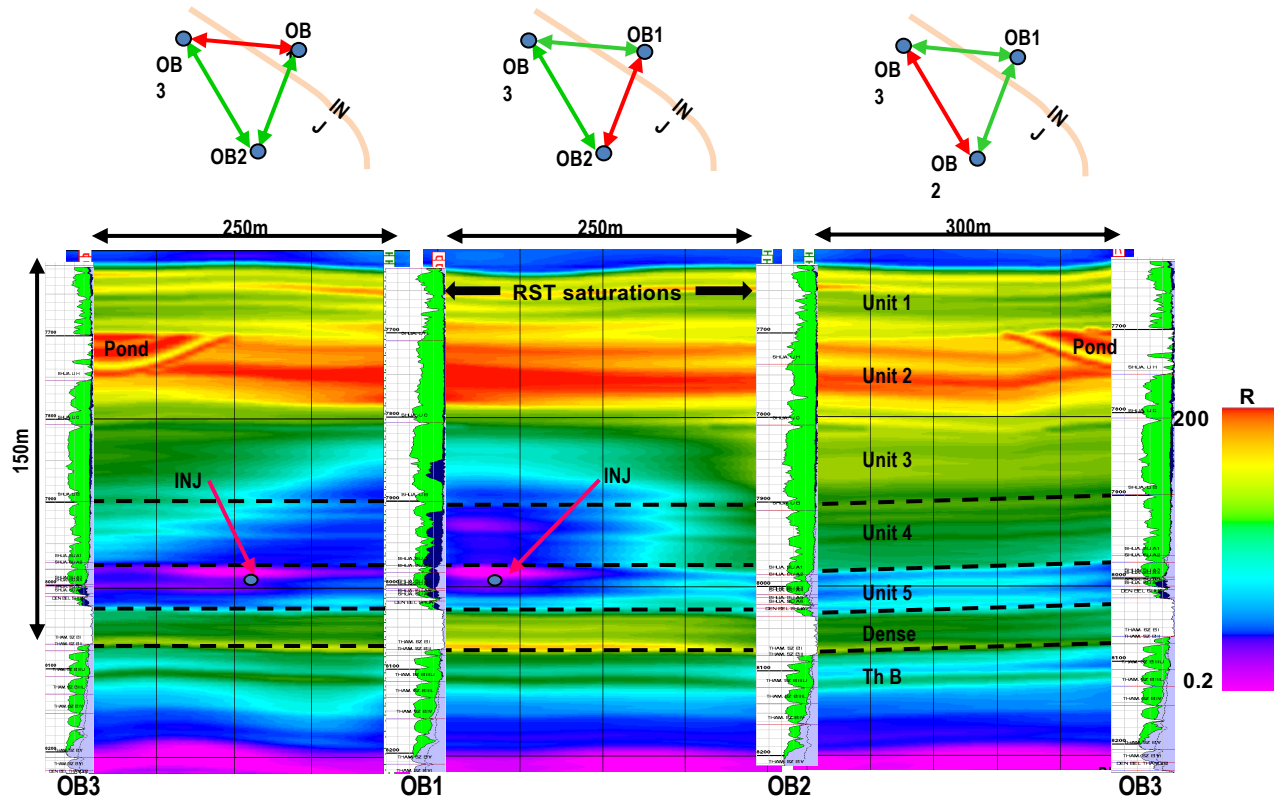
Time-lapse 1 (June 2008, after 6 months of injection)



Time-lapse 2 (December 2008, after 1 year of injection)

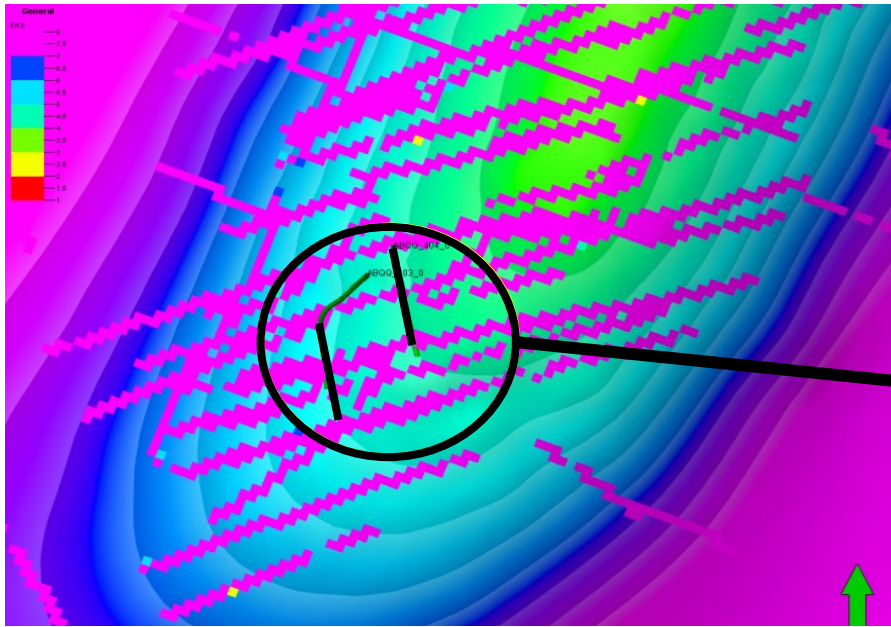


Time-lapse 3 (July 2009, after 1.5 years of injection)

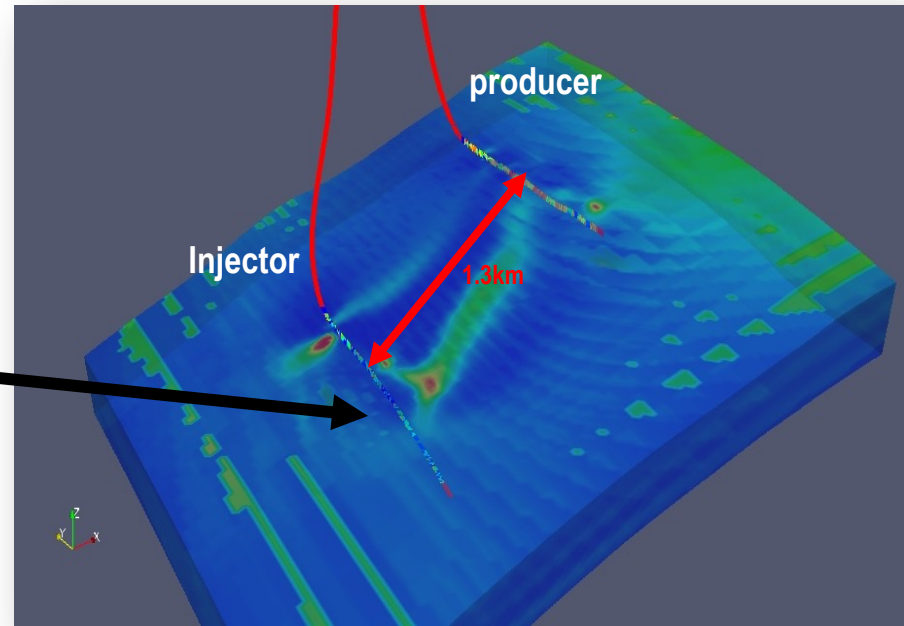


Time-lapse 4 (March 2010, after 2.3 years of injection)

Defining Fracture System and Locating by-passed Hydrocarbon



Reservoir is tight and highly fractured



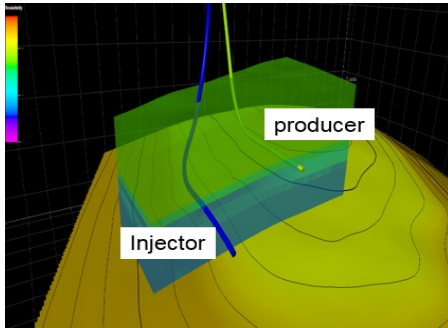
Water injection, 2000

Production shut down, 2013

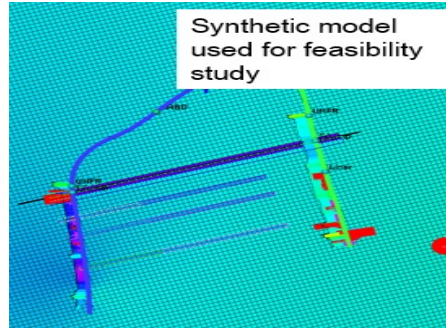
Mapping saturation distribution

Cross-well EM

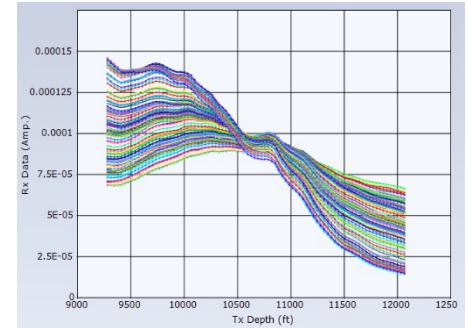
Project workflow:



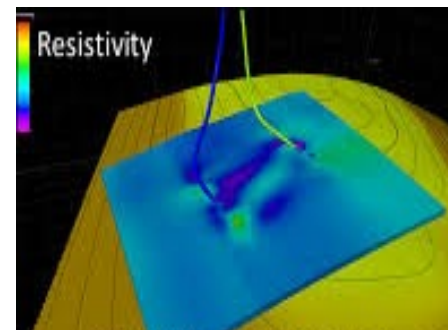
Project setup
2012



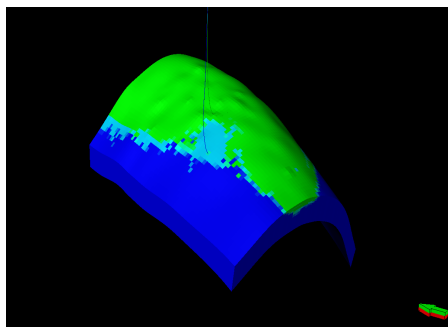
Simulation
2013



Data collection
2014

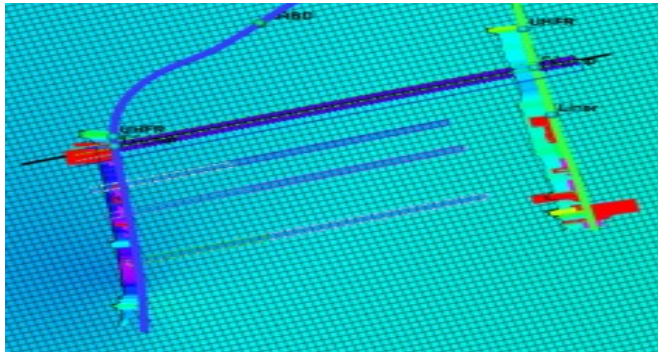
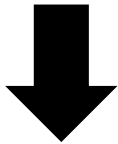
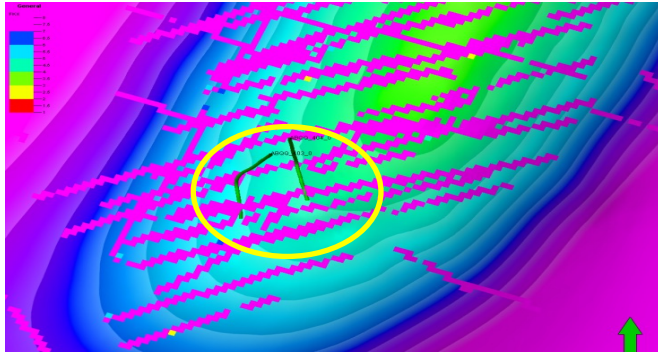


Resistivity Inversion
2015

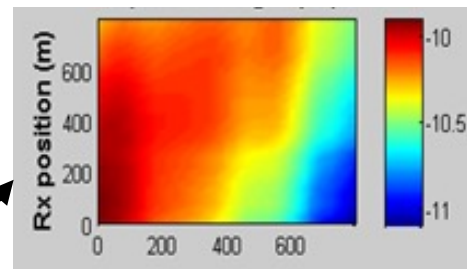


Water Saturation
Q3, 2016

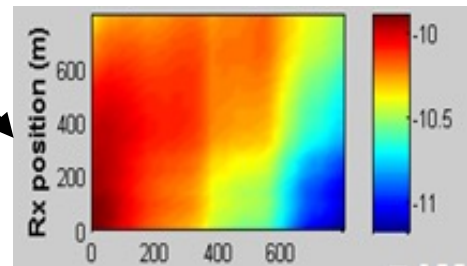
Pre-survey simulation (1)



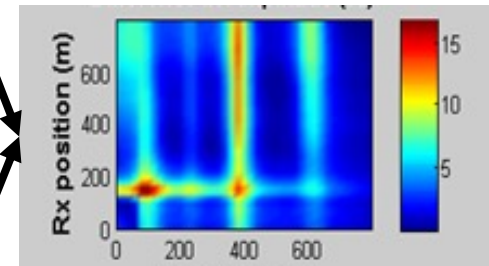
Without fractures



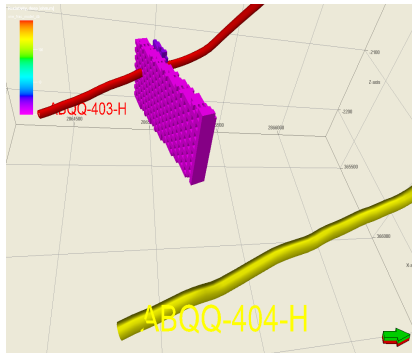
With fractures



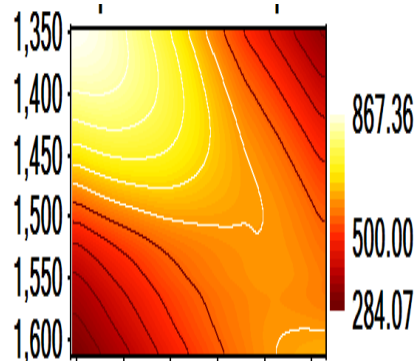
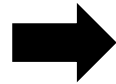
Difference



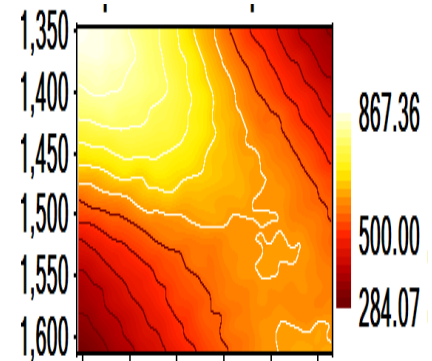
Pre-survey simulation (2)



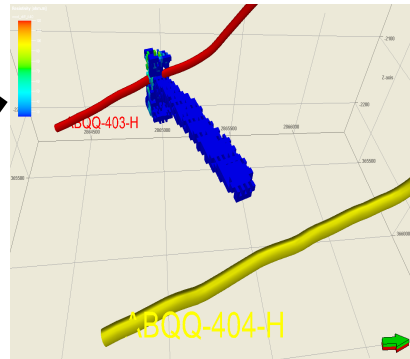
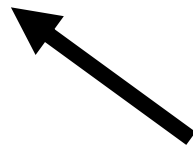
true model



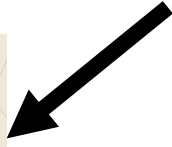
synthetic data



field-like data



Inverted model

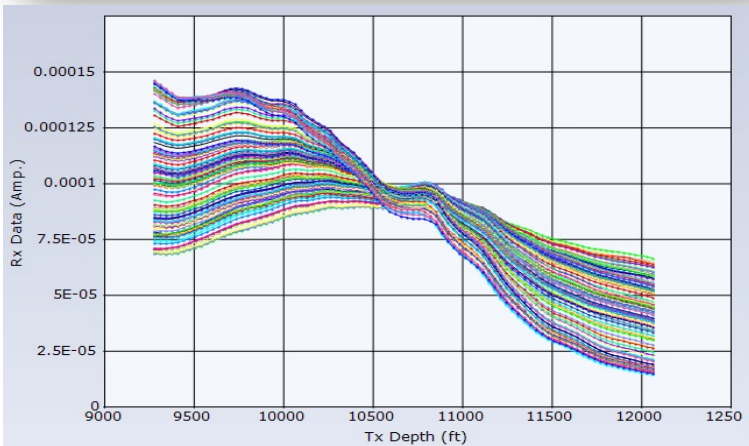




coiled-tubing conveyance

140 data profiles acquired

6 days field operations



High data quality

inversions

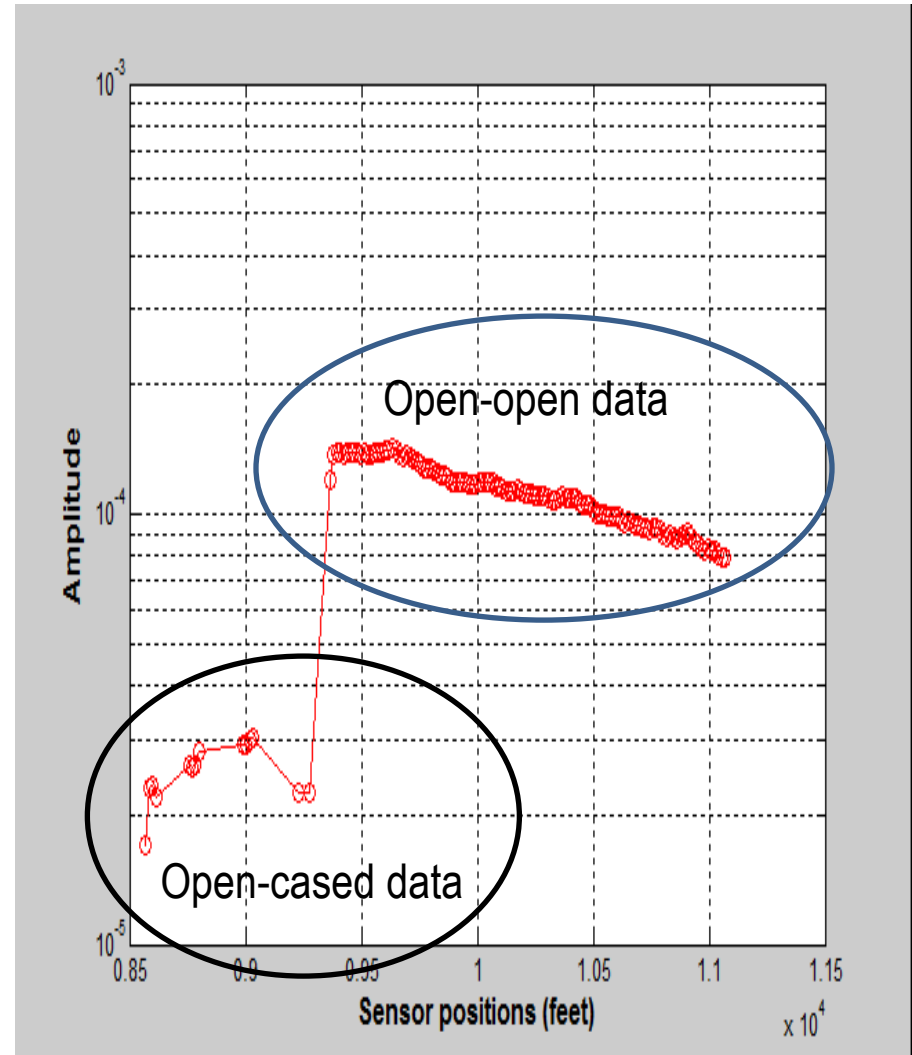
Resistivity structure

Inversion challenges

- ❑ How to integrate open-open and open-steel cased data
- ❑ How to handle 3D inversion with horizontal wells

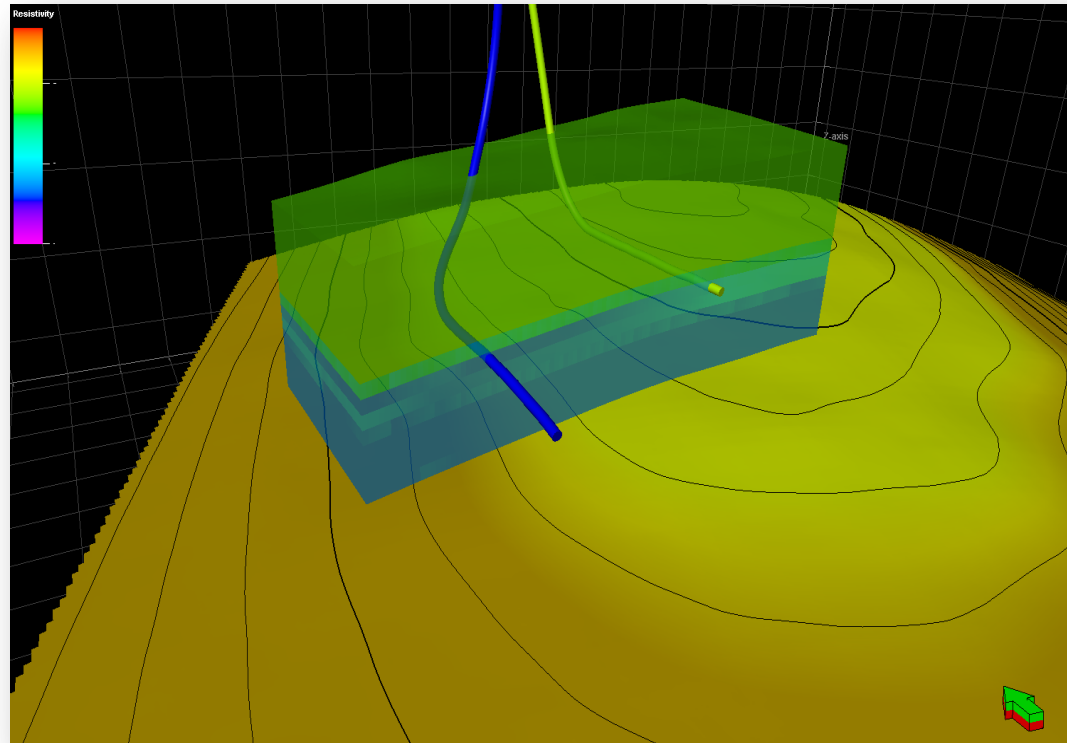
First challenge

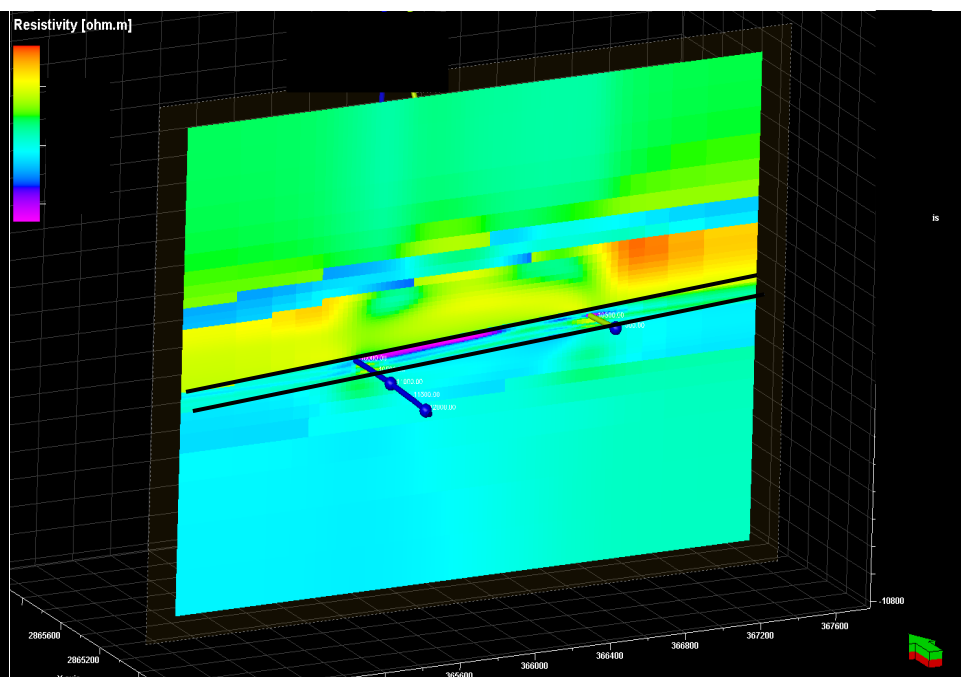
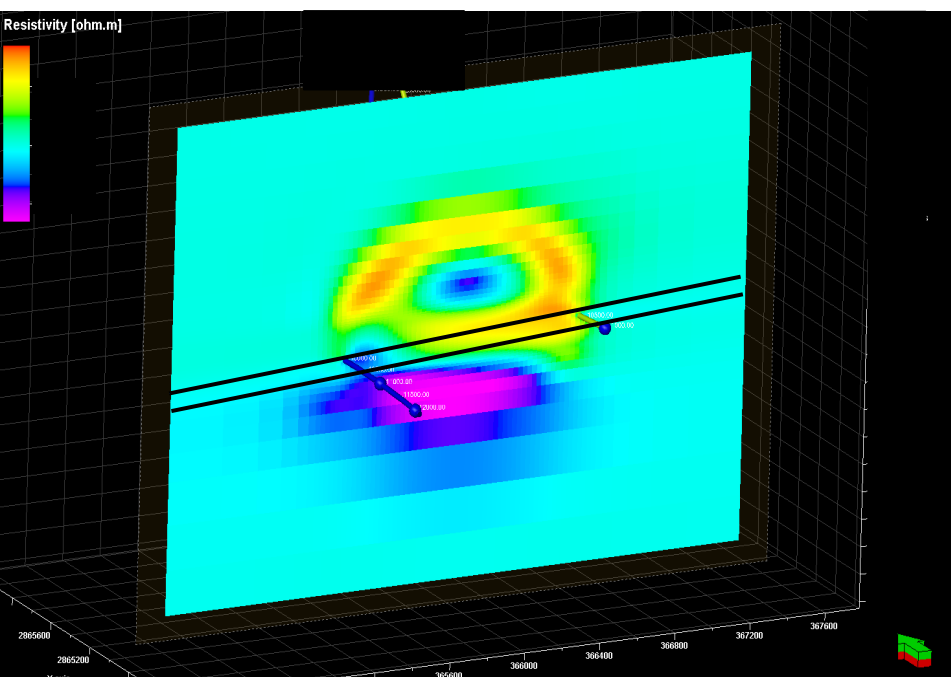
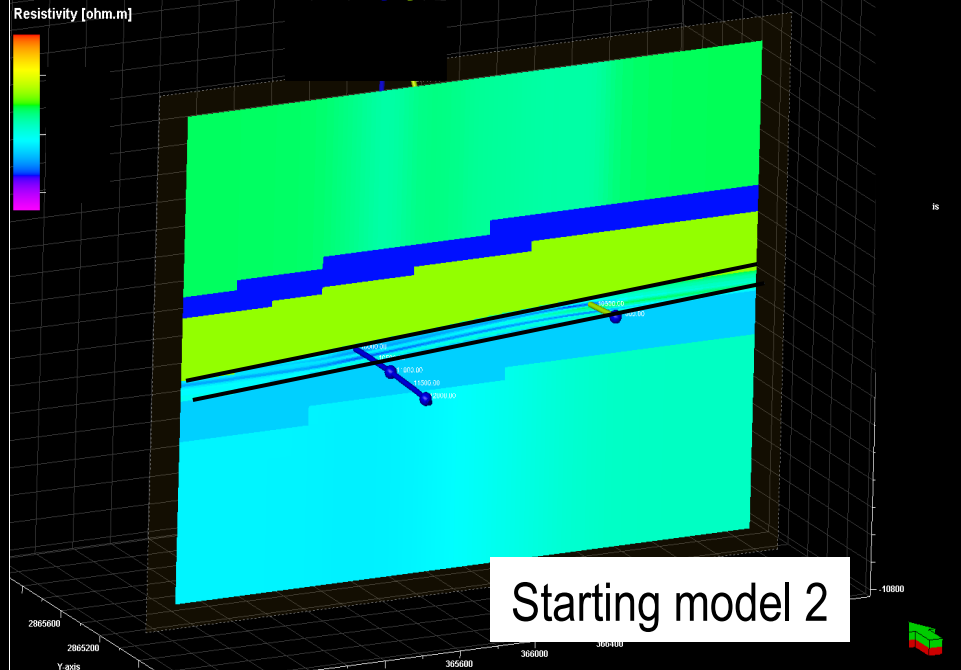
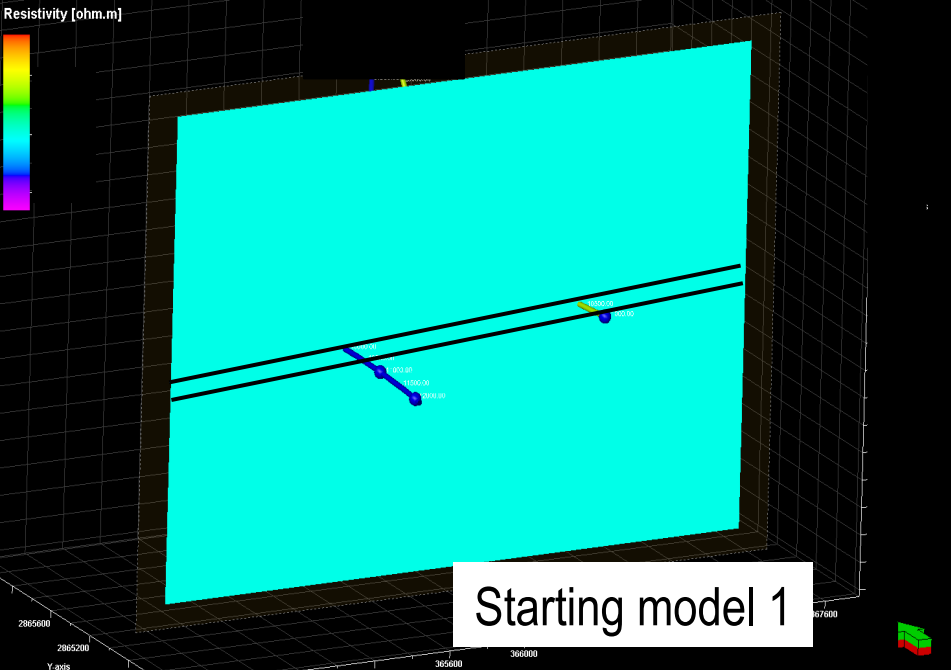
- ❑ Open-cased data is distorted
- ❑ Data correction has to be applied before inversion



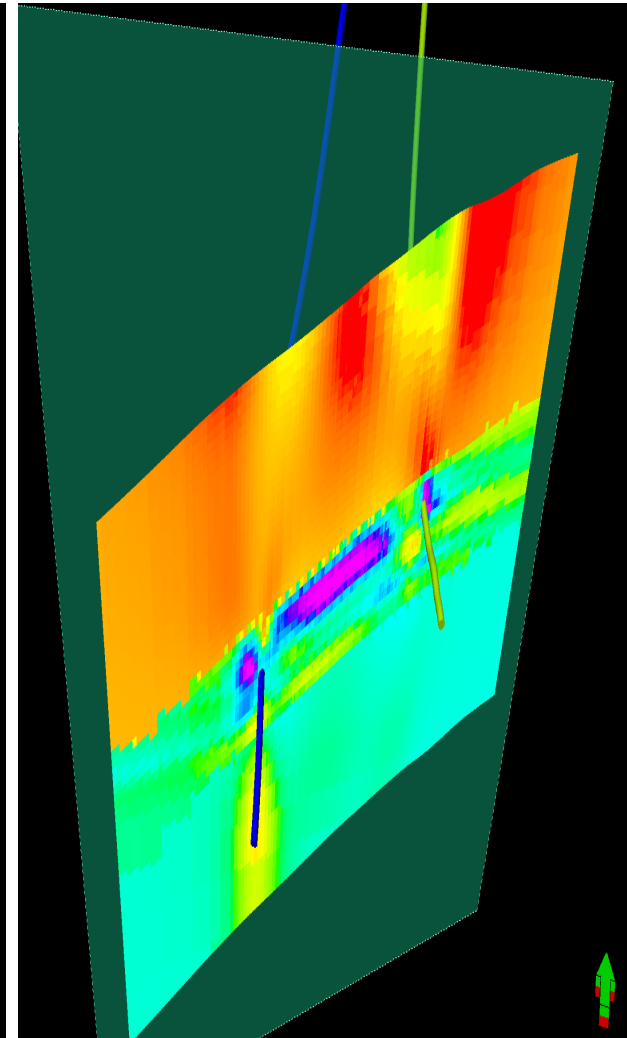
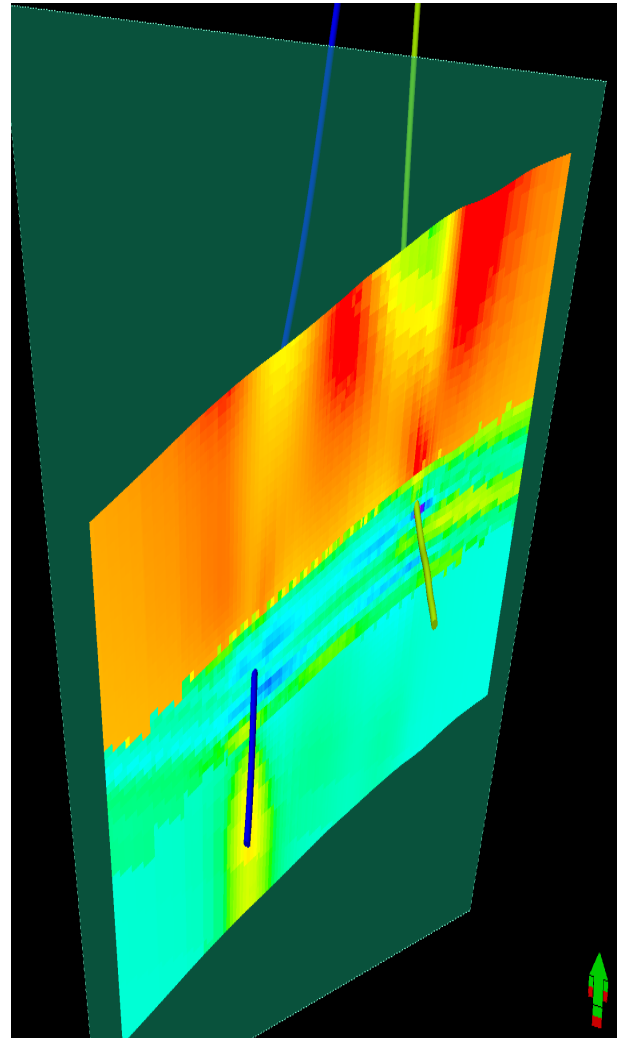
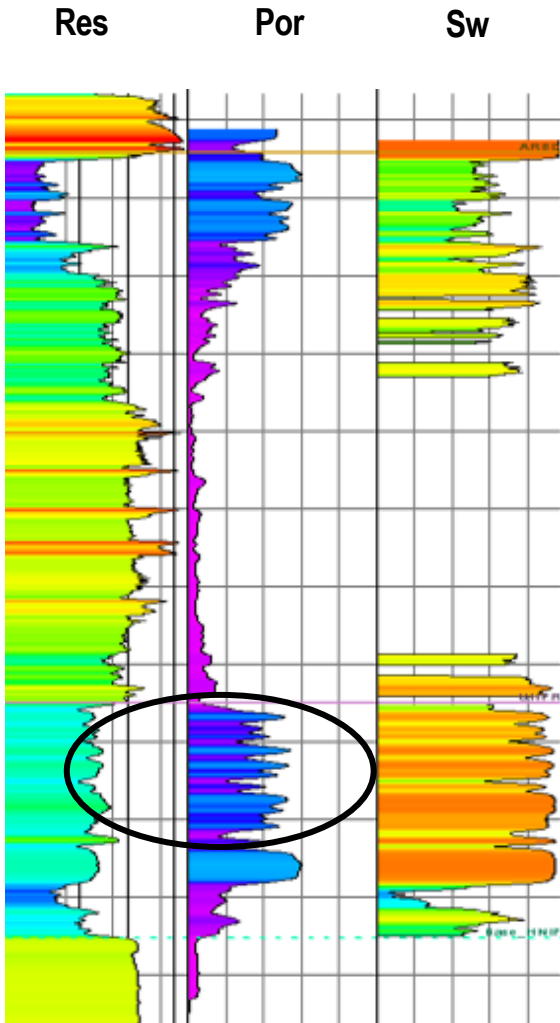
Second challenge

- ❑ Underdetermined problem:
 1. Model unknowns ~500,000
 2. Data points ~25,000
- ❑ Data are confined within thin reservoir
- ❑ Good starting model and constrains are needed to achieve useful inversion results





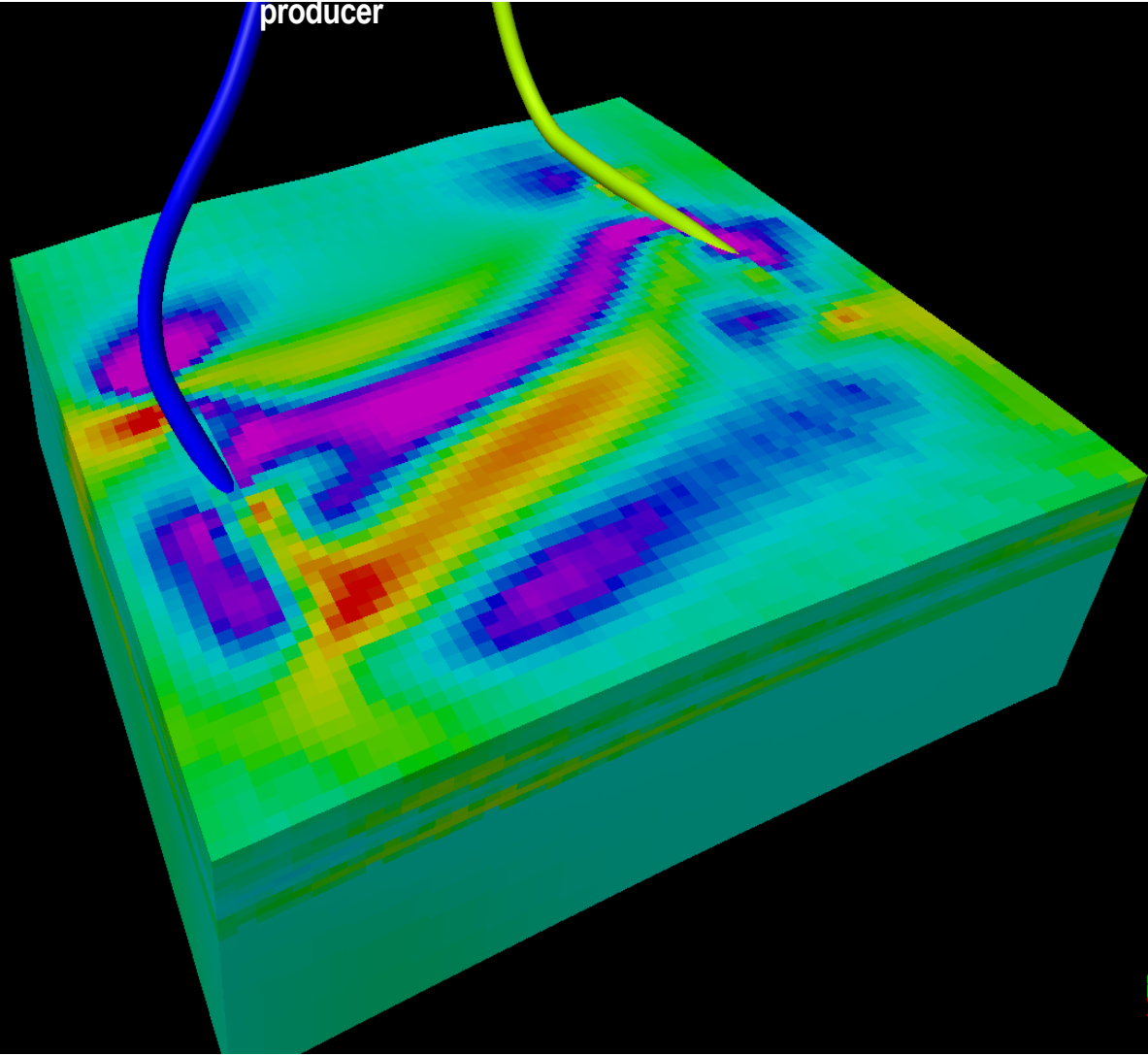
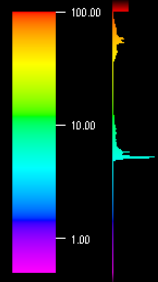
Interpretation Challenges: Inversion Non-Uniqueness

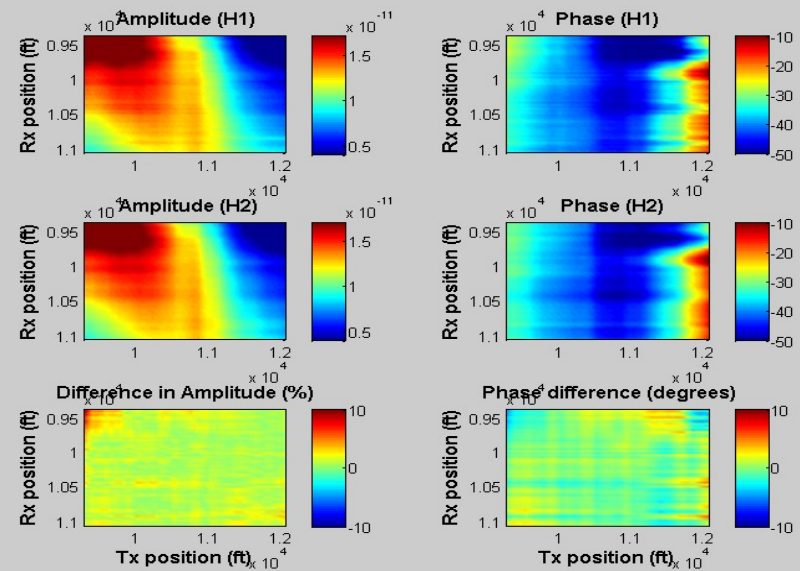
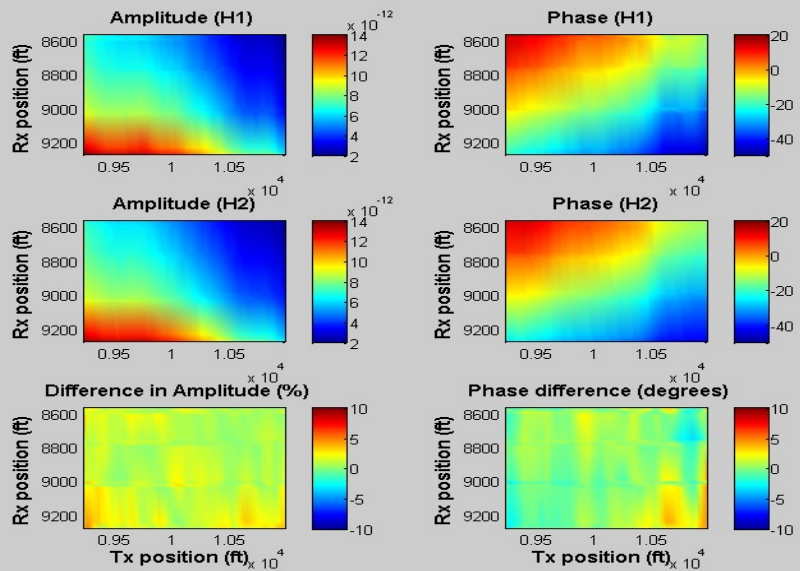


injector

producer

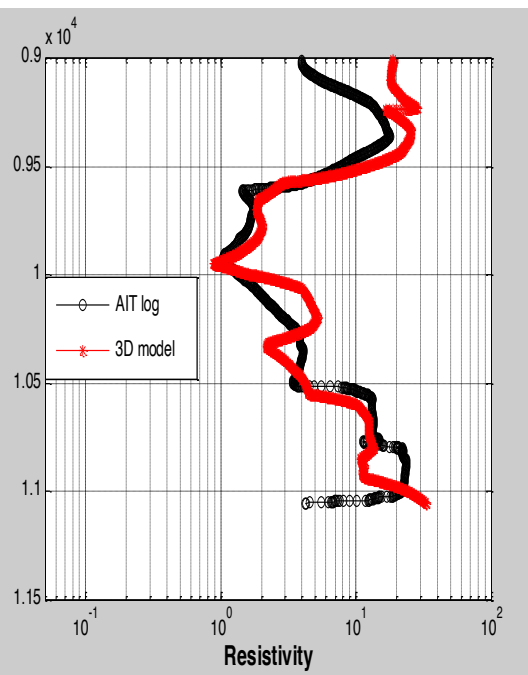
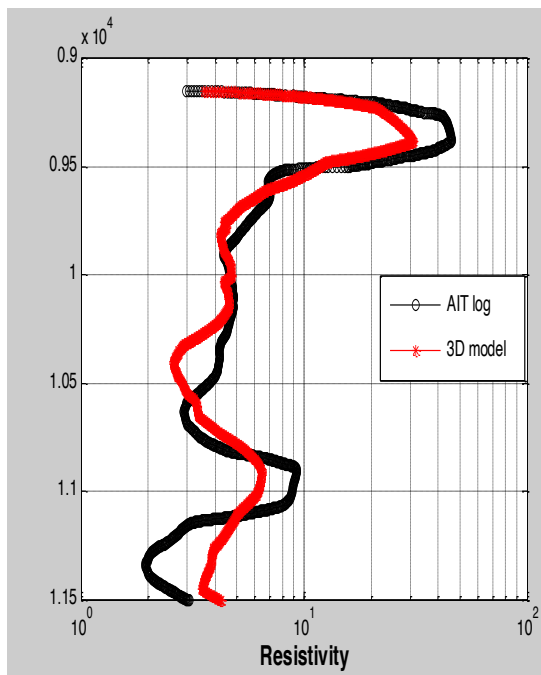
Resistivity (3dmodzz_it100)
Resistivity [ohm.m]





Data misfit for cased hole data

Data misfit for open hole data



Workflow (1)

Φ

R_t

R_w

n

m

The diagram illustrates the Archie equation for water saturation, S_w . The equation is presented as $S_w = \frac{a R_w}{\phi^m R_t}$. Red arrows point from descriptive labels to the variables in the equation:

- a : Empirical constant (usually near unity)
- R_w : Resistivity of formation water, $\Omega\text{-m}$
- ϕ^m : Porosity, fraction
- R_t : Resistivity of uninvaded formation, $\Omega\text{-m}$
- n : Saturation exponent (also usually near 2)
- m : Cementation exponent (usually near 2)

Water saturation, fraction

$S_w = \frac{a R_w}{\phi^m R_t}$

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S_w

Workflow (2)

Φ

R_t

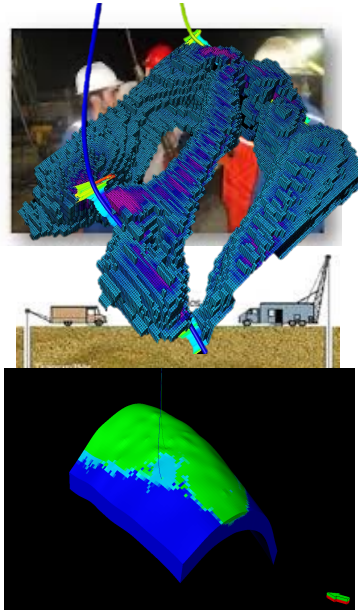
R_w

n

m



Porosity

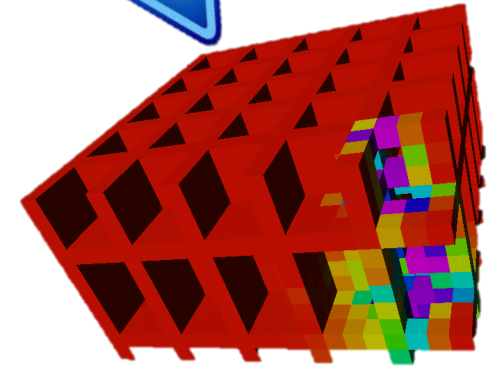


RT

S_w



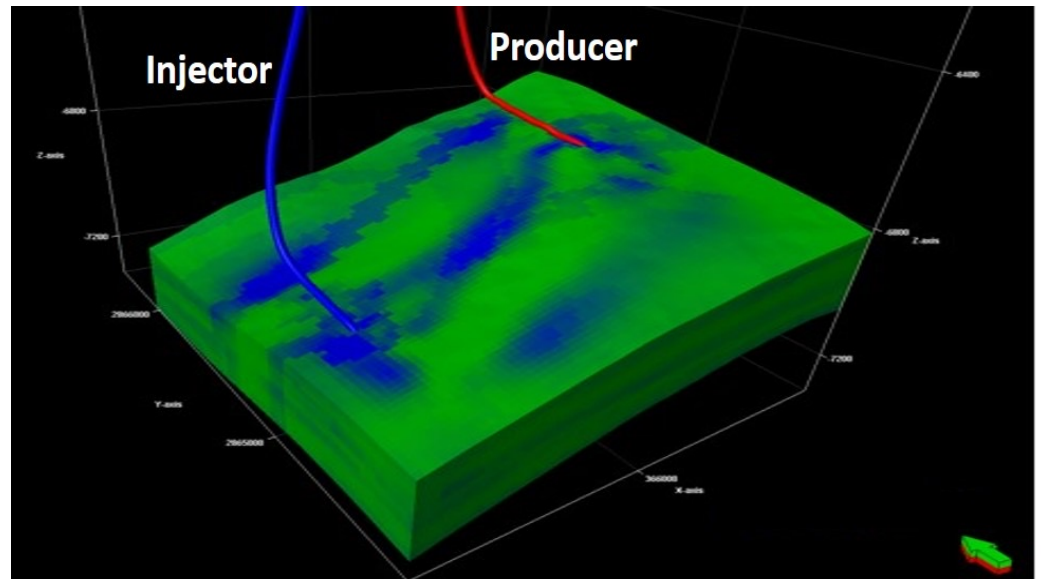
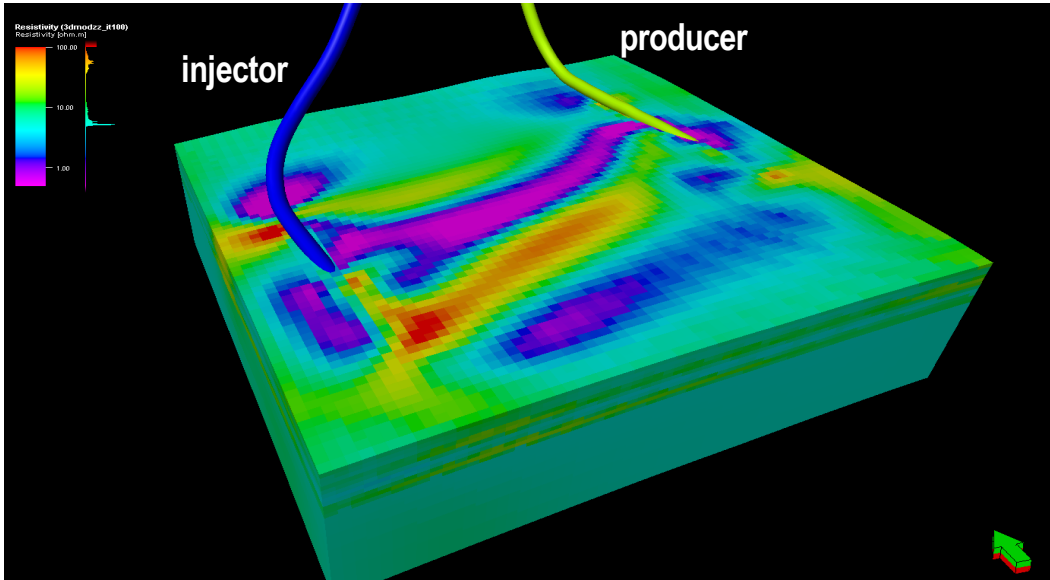
m & n

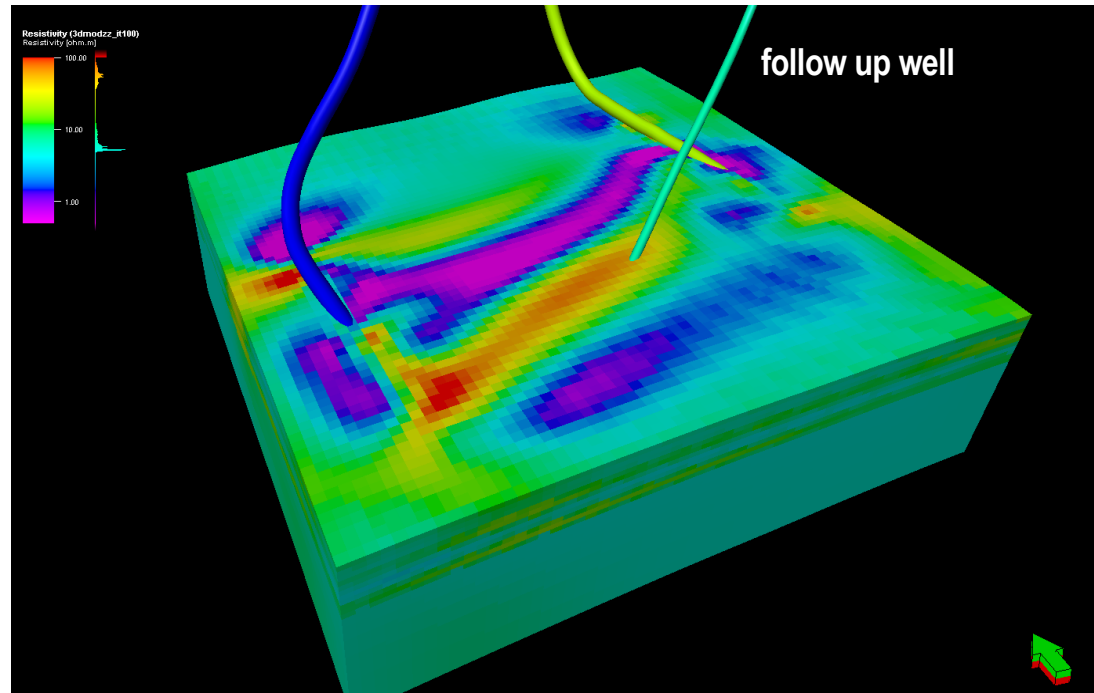
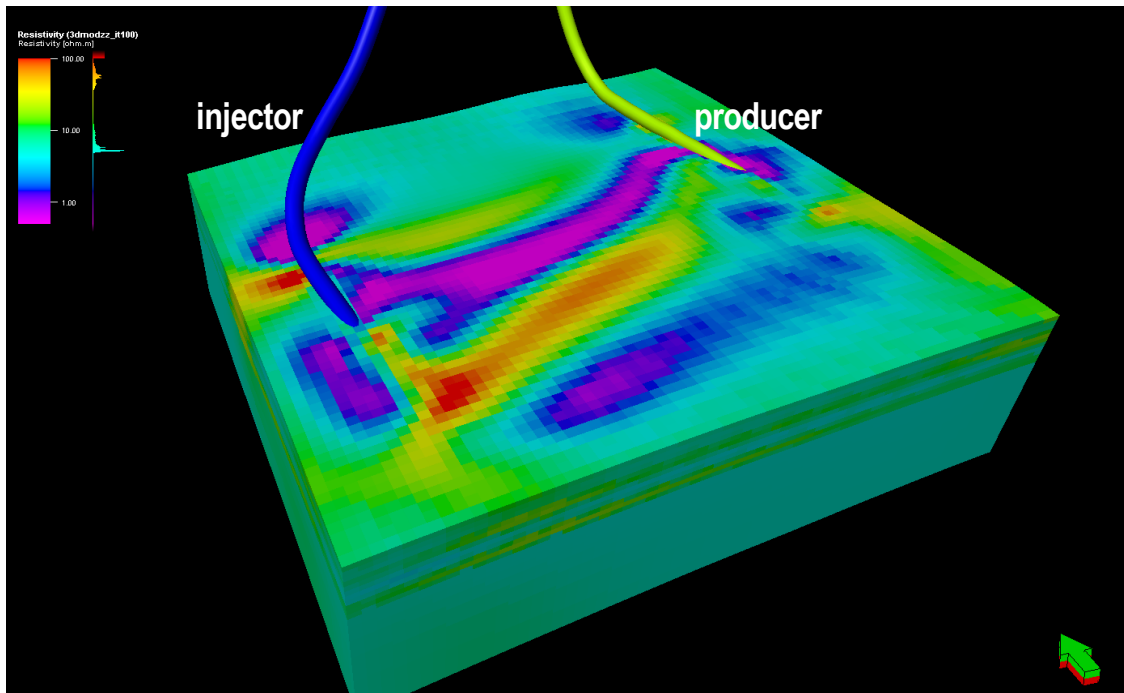


Salt Concentration $\rightarrow R_w$



Saturation mapping





Summary and conclusions

- Excellent resistivity imaging tool at reservoir scale
- Very efficient for monitoring fluid movements
- Capable to locate by-passed oil in a fractured reservoir
- Need two wells and providing 2D images
- Cannot work on two steel cased wells